

Lab 5: Week 1 - Getting Started

Purpose

The purpose of this laboratory exercise is to further our understanding of controlling sensors with a computer and using the computer for data acquisition, processing, and control of physical systems.

In this lab you will use thermocouple to measure and record temperature under the control of a Raspberry Pi computer interfaced through the General Purpose Input and Output (GPIO) pins. You will construct the circuit on a breadboard and write a Python script to control the sensor and record data locally. Then, you will connect to the JMU WiFi and construct additional Python code to write data to the cloud where it can be accessed by any device at any time. This will require several cyber security authentication protocols. Finally, you will use the thermocouple sensing system to activate an LED if a critical temperature is reached and send an alert to your cell phone via SMS text messaging.

Learning Goals

The goals of this Lab (all weeks together) are to:

- Review circuit concepts to physically connect measurement hardware to a computer
- Gain experience with General Purpose Input and Output pins (GPIO)
- Become familiar with Python programming used to control sensors and physical systems
- Investigate and evaluate measurement capabilities of a measurement instrument
- Calibrate the instrument
- Control sampling rate
- Calibrate the instrument (and estimate Type B calibration error)
- Determine an estimate of Type A (random) measurement uncertainty
- Write data to a local host computer
- Write data to the Cloud
- Use real-time automated decision making to control physical systems based on incoming data
- Send alerts wirelessly via WiFi and SMS communication protocols
- Report your findings in a formal lab report

This week, we will focus on the basic setup. At the end of the first lab exercise, you should be able to:

- collect temperature measurements using the thermocouple connected to the RPi

Background

Thermocouple sensors are used in a variety of applications to accurately measure temperatures. They are commonly used in industrial manufacturing to control chemical processes, such as fractional distillation of petroleum products and chemical synthesis of pharmaceuticals. They are used in personal computers to control cooling fans. They are used in HVAC systems to regulate temperature in houses, buildings, and large data centers. They are also used to monitor and control kiln temperatures in the firing of ceramics (extremely hot temperatures) and to monitor

storage of biological samples and temperature-sensitive biologically active substances (proteins, RNA/DNA, COVID vaccines, etc.)

The thermocouple is an extremely reliable instrument. It is based on the “Seebeck Effect”, which is a small voltage that occurs whenever two dissimilar metals are in contact. This voltage will change based on the temperature. When compared to a “reference temperature” at second junction of the two dissimilar metals, an absolute temperature measurement can be obtained. This voltage will be used to provide a measurement of temperature. A diagram of this process is shown in Figure 1.

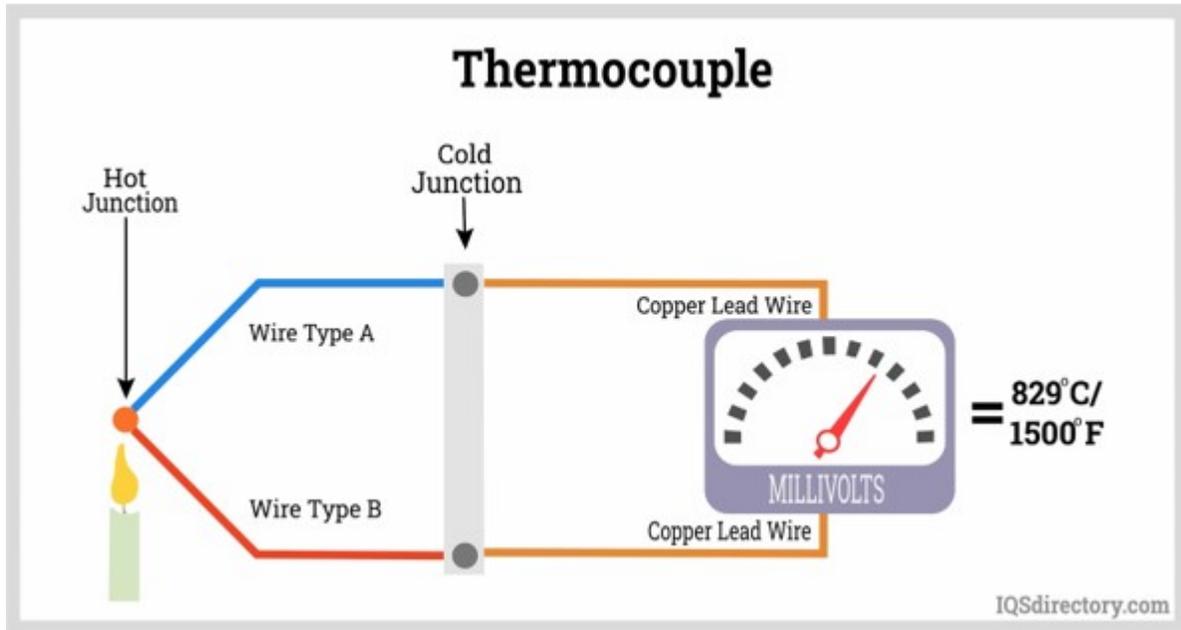


Figure 1: **How a thermocouple works** – Voltages are created at the junction of two dissimilar metals. The generated voltage will change with temperature.

For our lab, we will need to take this “analog” voltage output and digitize it in order for the signal to be sent to the Raspberry Pi computer. We will use an analog to digital converter to do this.

Methods

Connect the thermocouple sensor to the analog-to-digital converter

The thermocouple sensor will give an output voltage that corresponds to temperature. In order of this output voltage signal to be understood by the RPi, it must be converted to a digital signal (the RPi does not accept analog signals, only digital): We must use an **Analog-to-Digital converter (A/D board)**¹.

We will use the **MAX31856** A/D board. This board provides a reference temperature, converts the analog signal to digital, and **and** will do the mathematical conversions necessary to calculate temperature before sending the temperature reading to the RPi.

! Important: Connecting the thermocouple

Connect the thermocouple to the MAX31856 A/D board.

Unintuitively, Yellow is (+) and Red is (-). Be sure to get (+) and (-) correct.

¹ **A/D Converter**: A system that converts an analog signal (like a continuous voltage) into a digital signal (1s and 0s) that a computer can process.

Connect the thermocouple to the A/D board like in Figure 2:

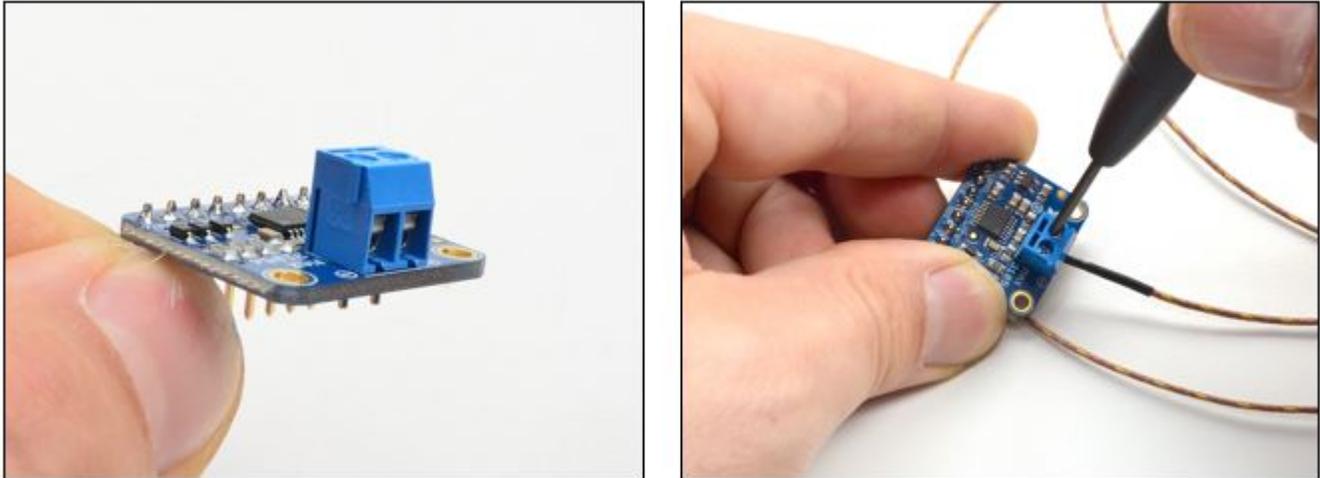


Figure 2: **Connecting the Sensor to the A/D board** - voltages from the thermocouple sensor must be converted from *analog* to *digital* to be used by the RPi

! Important

Make sure that the RPi is shut down before connecting the thermocouple.
Ask an instructor to get the wiring checked before turning it on.

Connect the RPi to the MAX31856 as shown in Figure 3.

Software configuration

In this lab, we will use **Python 3** and **CircuitPython**. Before writing our scripts, we must ensure the Raspberry Pi is updated and install the necessary python packages.

You will be using the command line to perform these installations and checks.

1. **Linux Terminal:** Open a terminal window by clicking on this icon in the upper left of the control bar (Figure 4). This opens the *command line*, which will be used to enter your commands.

2. **Installation Commands:**

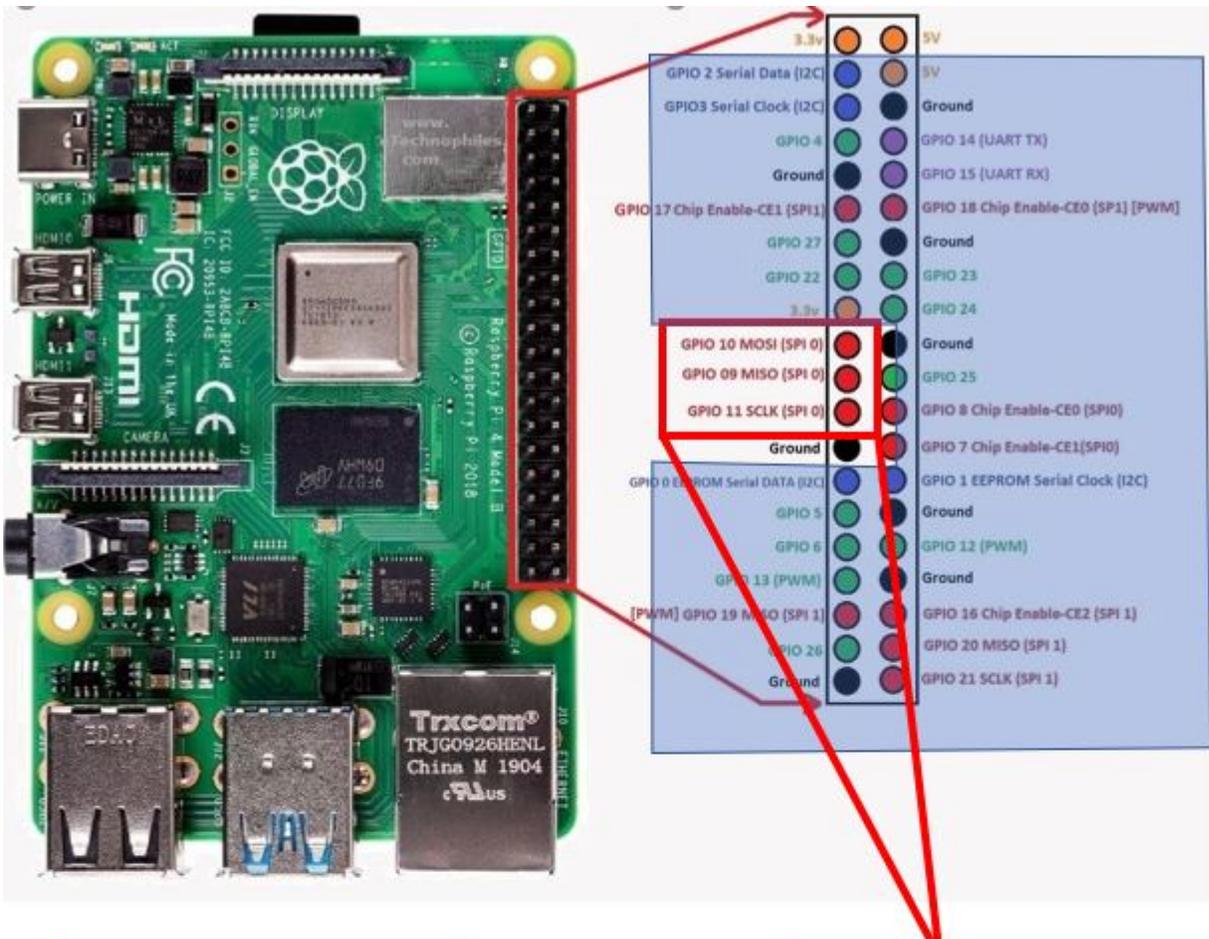
Run the following commands in your terminal. Type them exactly as shown (or copy them over) and press *Enter* after each line

```
# 1. Update the system package list and upgrade current software
sudo apt-get update
sudo apt-get upgrade -y

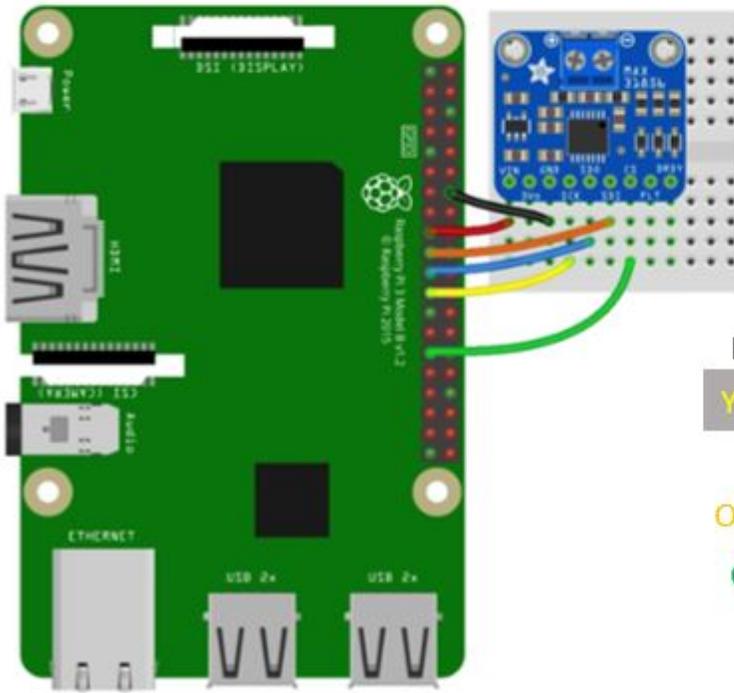
# 2. Install the virtual environment creator
sudo apt-get install python3-venv -y

# 3. Create a virtual environment named 'lab5_env'
python3 -m venv lab_env

# 4. Activate the virtual environment (as root)
sudo su
```



These are the SPI pins we will connect to



- Red Pi 3V to sensor VIN
- Black Pi GND to sensor GND
- Yellow Pi SCK to sensor SCK
- Blue Pi MISO to sensor SDO
- Orange Pi MOSI to sensor SDI
- Green Pi D5 to sensor CS (or any other free digital I/O pin)

Figure 3: MAX31856 Wiring Instructions

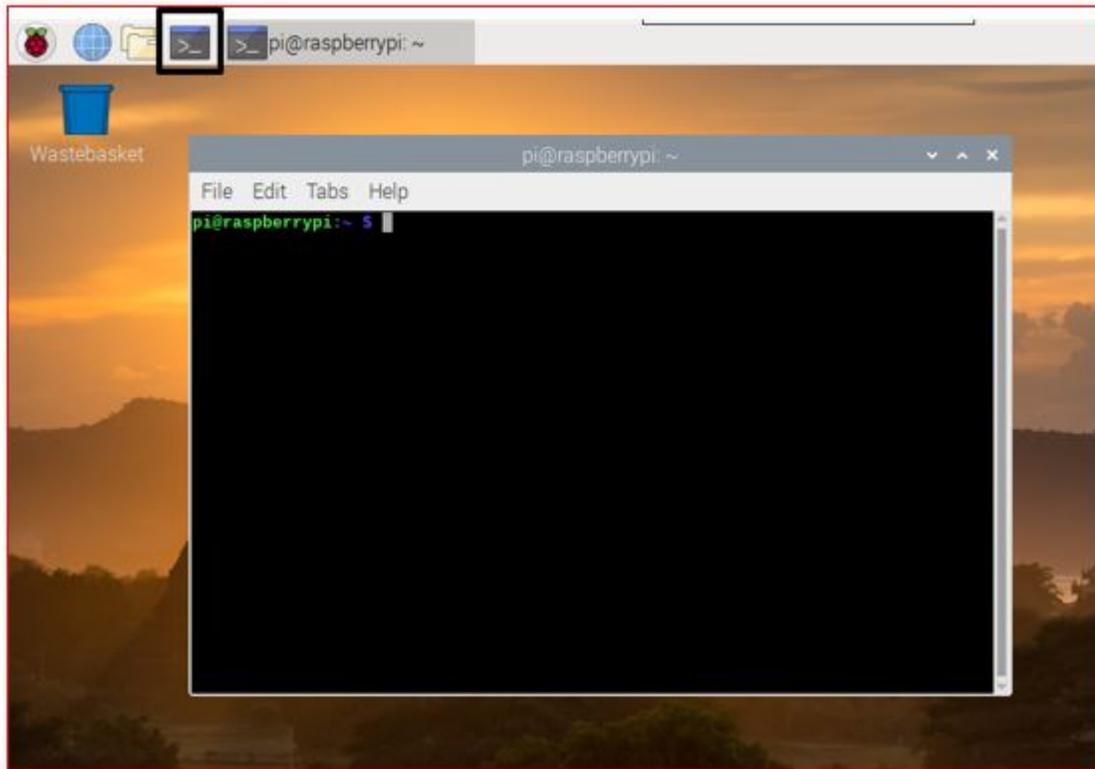


Figure 4: The Terminal window on the Raspberry Pi where to enter system commands

```
source lab_env/bin/activate
# CHECK: Your terminal prompt should now start with (lab_env)

# 5. Install the Adafruit Python Shell library
pip3 install adafruit-python-shell

# 6. Install the Raspberry Pi GPIO
pip3 install RPi.GPIO
```

i Helpful definitions

- **sudo**: *super user do*, grants temporary admin rights. Anything executed with **sudo** can have serious consequences as system files are being changed.
- **apt-get**: package manager for linux, which is used to install and maintain new software
- **apt-get update**: **apt** checks for updates of installed software on the internet
- **apt-get upgrade**: **apt** fetches and installs any available system updates
- **virtual environment**: A self-contained directory that contains a specific Python installation. It prevents conflicts between different projects. It is used to keep of lab libraries separate from the system-wide Python installation. This is good practice, because **pip** – the Python package manager – does not check for conflicts between installed python libraries. This means installing Python packages via **pip** or **pip3** can break the entire Python installation.

Software Connection: Blinka

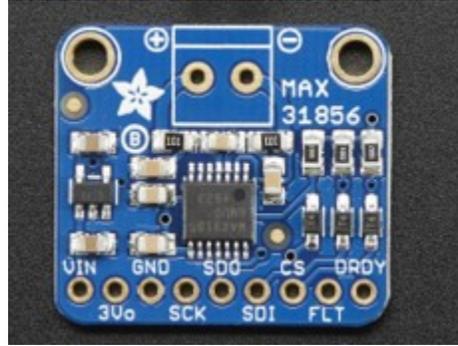


Figure 5: MAX31856 A/D Converter

The MAX31856 uses **CircuitPython**, but the RPi runs standard **Python 3**. To bridge this gap, we use a library called **Blinka**. Blinka translates the hardware API² calls.

In order to be able to communicate between the RPi and MAX31865, we will need to install a package called *Blinka* (Figure 6) to connect the two systems.

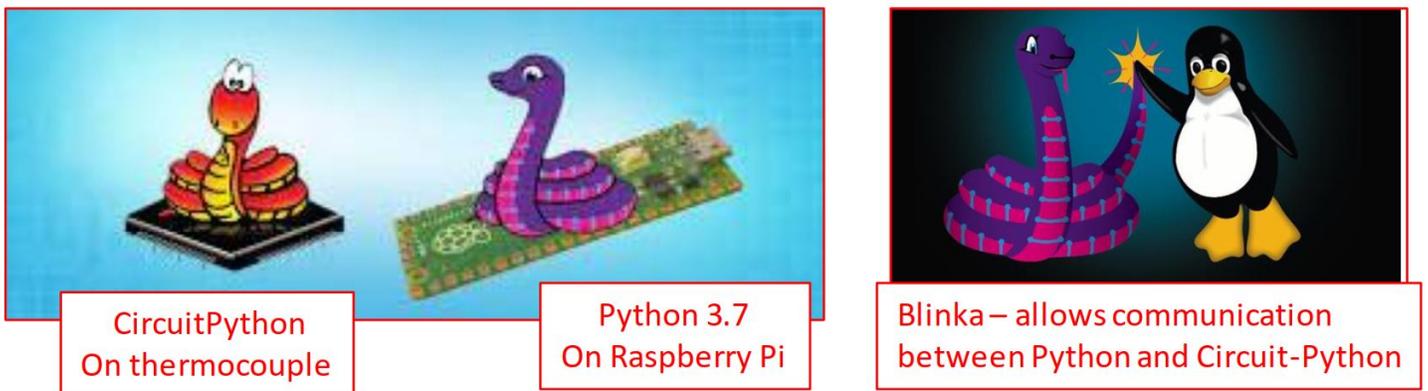


Figure 6: Blinka acts as a bridge between Circuit Python on the A/D board and the standard Python on the RPi

! Important

Ensure your terminal is open and your virtual environment is active (look for (lab_env)).
If you have closed the terminal and you open another one, you will have to redo the activation step:

```
sudo su
source lab_env/bin/activate
```

1. **Download the *blinka* installation script:** Type the following command (it is one long line):

```
wget https://raw.githubusercontent.com/adafruit/Raspberry-Pi-Installer-Scripts/main/raspi-blinka
```

i Helpful terminology

- `wget` is a command to download (*get*) a file from the web.

²**API** (Application Programming Interface): A set of protocols that allows different software components to talk to each other.

So the next two commands, will install the python-shell and then download a *python* script to install **blinka**.

2. Run the script (make sure you activate the virtual env as sudo)

```
python3 raspi-blinka.py
```

i Note

Note: If prompted to reboot, allow the system to reboot. After rebooting, remember to reactivate your environment: `source lab_env/bin/activate`

3. Software connection test (make sure you activate the virtual env as sudo)

Download the a test program for blinka from my GitHub using `wget` and run the program from the command line.

```
wget https://raw.githubusercontent.com/TobGerken/ISAT300/main/LabCode/blinka-test.py
```

```
python3 blinka-test.py
```

This is how the test program looks:

```
import board
import digitalio
import busio

print("Hello blinka!")

# Try to great a Digital input
pin = digitalio.DigitalInOut(board.D4)
print("Digital IO ok!")

# Try to create an I2C device
i2c = busio.I2C(board.SCL, board.SDA)
print("I2C ok!")

# Try to create an SPI device
spi = busio.SPI(board.SCLK, board.MOSI, board.MISO)
print("SPI ok!")

print("done!")
```

If everything is working correctly, you should see the below output printed to the terminal

```
Hello Blinka
Digital IO ok!
I2C ok!
SPI ok!
done!
```

Software Connection: MAX31856 Library

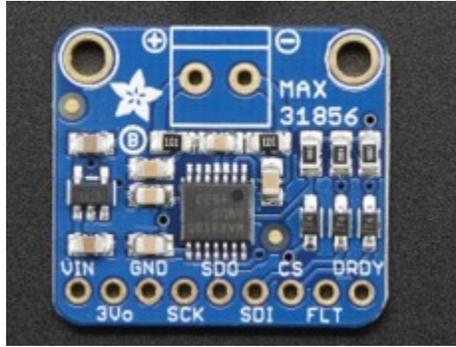


Figure 7: MAX31856 A/D Converter

The MAX31856 is more than just an analog to digital converter. The chips on this small circuit board will also provide a reference temperature for the thermocouple and are pre-programmed to convert the voltage signal into a temperature reading.

Adafruit (the company that makes this board) has also provided Python packages that we will need to install on the RPi to make the system work.

1. In the `terminal` and execute the below command to install the `MAX31856`

```
sudo su
source lab_env/bin/activate
pip3 install adafruit-circuitpython-max31856
```

Thermocouple Python Interface

💡 Tip: File and Code Hygiene

It is good practice to

- create a dedicated folder for your work, where you save all files that belong to a given project. This means e.g. a folder for ISAT300 that contains subfolders for each lab.
- save all files to disk with sensible names
- use *typical* file extensions, such as `<filename>.py` for *Python* files.

1. Open the *Thonny* IDE and obtain the Lab 5 StarterCode from my GitHub:

[Lab 5 Starter Code](#)

2. Complete the missing lines so that the code matches the image below

```
ISAT300_Lab5_Part1.py x
1 *****
2 # importing packages already on the RPi into this Python program *
3 *****
4
5 import board
6 import busio
7 import digitalio
8 import adafruit_max31856
9
10 *****
11 # Setting up the thermocouple *
12 *****
13 # This part of the code is difficult to understand, but
14 # in essence it creates an object that allows python to communicate
15 # with the thermocouple.
16
17 # create an SPI object
18 spi = busio.SPI(board.SCK, board.MOSI, board.MISO)
19
20 # allocate a Chip Select pin for the thermocouple (CS pin) and set the direction
21 cs = digitalio.DigitalInOut(board.D5)
22 cs.direction = digitalio.Direction.OUTPUT
23
24
25 # create a thermocouple object with the above
26 thermocouple = adafruit_max31856.MAX31856(spi, cs)
27
28 *****
29 #** reading the thermocouple and printing output on screen *
30 *****
31
32 temperature = thermocouple.temperature
33
34 print(temperature, "C")
35 |
```

```
Shell x
Python 3.10.11 (C:\Users\gerkentx\AppData\Local\Programs\Thonny\python.exe)
>>>
```

Local Python 3 • Thonny's Python

! Important

Before running the code, you must configure Thonny to use your virtual environment. Go to *Tools* → *Options* and select the Interpreter tab. Near the dropdown (under Python Executable) click the 3 dots, a window opens, navigate to your virtual environment, and select the python3 file located inside the lab_env/bin/ directory. Click **OK**, then run your code.

If the above is confusing, there is another way. Because our required libraries are installed in a virtual environment, you could only use Thonny as a text editor. To run your code, open a terminal window, ensure your virtual environment is activated (you should see (lab_env) at the start of your prompt), and run the script by typing: `python3 your_script_name.py`

Code definitions

- Import `board`: CircuitPython module to provide access to board specific pins
- Import `busio`: Handles **SPI**³ communication
- `digitalio`: CircuitPython module to control the input/output for our Chip Select pin
- Creating the object `thermocouple` allows python to query the temperature from the thermocouple object by accessing the `thermocouple.temperature` attribute, which provides the thermocouple temperature in °C.

³*SPI* (Serial Peripheral Interface): A high-speed, 4-wire communication protocol used for short distances

Unit Conversion Challenge

The default output is in Celsius.

Add the following line to the end of your script to convert it to Fahrenheit:

```
print(str(temperature * 9 / 5 + 32), "F")
```

Acknowledgements

This Lab was prepared by Dr. Chris Bachmann. Special thanks to Joe Rudmin for obtaining necessary supplies and facilitating the lab setup.

Revision	Description	Author
2024-03-01	Post lab updates for error fixes and tips	Tobias Gerken
2024-02-23 (S24)	Updated to Web, changes to sample code and images	Tobias Gerken
	Initial Version	Chris Bachmann